

## Frobenius theorem

1. Let  $X = \frac{\partial}{\partial x} + f \frac{\partial}{\partial z}$  and  $Y = \frac{\partial}{\partial y} + g \frac{\partial}{\partial z}$  be two vector fields on  $\mathbb{R}^3$  and  $\Delta = \text{span}\{X, Y\}$ . Show that  $\Delta$  is integrable iff

$$\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} + f \frac{\partial g}{\partial z} - g \frac{\partial f}{\partial z} = 0$$

### Miscellaneous

2. Find an example of a complete metric space  $X$  (for example,  $\mathbb{R}$ ) and a function  $f : X \rightarrow X$  such that  $d(f(x), f(y)) < d(x, y)$  whenever  $x \neq y$ , but  $f$  does not have any fixed points.
3. Let  $X, Y$  be two vector fields on a manifold  $M$ . Show that

$$L_{[X, Y]} = [L_X, L_Y]$$

where  $L_{[X, Y]}$  is the Lie derivative of vector fields with respect to the Lie bracket  $[X, Y]$  and  $[L_X, L_Y]$  is the commutator  $L_X L_Y - L_Y L_X$ . Hint: Recall the Jacobi identity.

4. The formula  $L_{[X, Y]} = [L_X, L_Y]$  is also true when  $L$  is viewed as an operator on forms, but the proof is harder. Follow the usual strategy:
  - (a) Show that if  $L_{[X, Y]}\omega_i = [L_X, L_Y](\omega_i)$  for  $i = 1, 2$  then  $L_{[X, Y]}\omega = [L_X, L_Y](\omega)$  for  $\omega = \omega_1 \wedge \omega_2$ . This is formal, using the Leibnitz rule.
  - (b) Show that  $L_{[X, Y]}\omega = [L_X, L_Y](\omega)$  when  $\omega$  is a 0-form (i.e. a function).
  - (c) Show that  $L_{[X, Y]}\omega = [L_X, L_Y](\omega)$  when  $\omega = dx_i$  (in local coordinates). You can use Cartan's Magic Formula, which will be particularly simple here since one of terms will be 0.
5. Let  $X, Y$  be two vector fields on a manifold  $M$  and assume  $X(p) = Y(p) = 0$  for some  $p \in M$ . Show that  $L_X Y(p) = 0$ .
6. Let  $X_t$  for  $t \in \mathbb{R}$  be a 1-parameter family of vector fields on  $\mathbb{R}^n$ . By this I mean that the function  $(x, t) \mapsto X_t(x) \in \mathbb{R}^n$  is a smooth function  $\mathbb{R}^n \times \mathbb{R} \rightarrow \mathbb{R}^n$ . We also refer to  $X_t$  as a *time dependent vector field*. A curve  $c : (a, b) \rightarrow \mathbb{R}^n$  is an integral curve of  $X_t$  provided  $c'(t) =$

$X_t(c(t))$ . The following trick reduces the existence problem to the existence of integral curves for the usual vector fields. Define a vector field  $Y$  on  $\mathbb{R}^n \times \mathbb{R}$  by  $Y(x, t) = X_t(x) + \frac{\partial}{\partial t}$ . Thus the  $\mathbb{R}$ -component is always  $\frac{\partial}{\partial t}$  and the  $\mathbb{R}^n$ -component at level  $t$  is given by  $X_t$ . Let  $\alpha$  be an integral curve of  $Y$ . Show that the projection of  $\alpha$  to  $\mathbb{R}^n$  is an integral curve of  $X_t$ . This implies existence and uniqueness theorems about equations of the form  $y' = F(y, t)$ .

7. In a similar way, higher order ODE's can be reduced to integrating vector fields. The usual ODE giving a vector field has the form  $y' = F(y)$  and then we use  $F$  to define the vector field. For example, suppose we have an equation  $y'' = F(y, y')$ . Show that this can be reduced to integrating a vector field on  $\mathbb{R}^n \times \mathbb{R}^n$  by introducing a new variable  $z$  that represent  $y'$  and the equation is

$$\begin{pmatrix} y \\ z \end{pmatrix}' = \begin{pmatrix} z \\ F(y, z) \end{pmatrix}$$

In general, differential equations of the form  $y^{(n)} = F(t, y, y', \dots, y^{(n-1)})$  can be reduced to integrating vector fields.